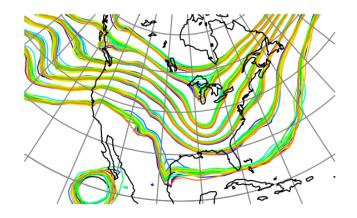


DART Tutorial Section 18: Lost in Phase Space: The Challenge of Not Knowing the Truth.





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Reality Strikes

In real applications, the truth is unknown.

All that we have are observations.

Having the truth available has been convenient, but also misleading.

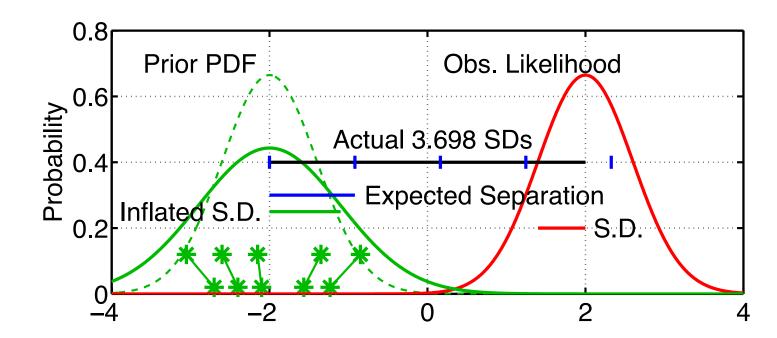
Much less information is available from the observations.

They are generally functions of the state variables.

They are always contaminated with observational errors.

What to expect ...

Recall that Expected(prior_mean – observation) =
$$\sqrt{\sigma_{prior}^2 + \sigma_{obs}^2}$$



Error is dominated by observational noise if $\sigma_{obs}^2 \gg \sigma_{prior}^2$ Suppose $\sigma_{obs} = 1.0$, $\sigma_{prior} = 0.1$, then E(RMS) = 1.005. Halving σ_{prior} to 0.05 => E(RMS) = 1.001; only a 0.4% reduction!

First Observation-space diagnostics:

Whether or not to assimilate or reject observations based on their Expected Separation is controlled during *filter* based on namelist settings in *input.nml*.

If
$$|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$$
 $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{prior}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{obs}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{obs}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{obs}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{obs}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$ $|\overline{y^p} - y^o| / \sqrt{\sigma_{obs}^2 + \sigma_{obs}^2} > \text{outlier_threshold}$

The program **obs_diag** post-processes **obs_seq.final**, calculates metrics like RMSE, bias, ensemble spread, totalspread, # of observations used or rejected ... Start with the *lorenz_96* model.

Observation-space diagnostics

The observation sequence file is not in a particularly user-friendly format. To aid in the evaluation and interpretation, a program named **obs_diag** must be run to produce a netCDF file with results that can be plotted in a manner of your choosing. DART has Matlab functions/scripts that create high-quality graphics. For up-to-date information on the latest, greatest diagnostics, go to: http://www.image.ucar.edu/DAReS/DART/DART2 Diagnostics.php#obs_diagnostics

```
&obs diag nml
  obs sequence name = 'obs seq.final',
               = -1,
  bin width days
  bin width seconds = -1,
  init skip days
                             (Slightly different for 3D models.)
  init skip seconds = 0,
  Nregions
                    = 3,
  trusted_obs = 'null',
  lonlim1 = 0.00, 0.00, 0.50, -1.0
  lonlim2 = 1.01, 0.50, 1.01, -1.0
                     = 'whole', 'yin', 'yang', 'bogus,
  reg names
  create rank histogram = .true.,
  outliers in histogram = .true.,
  use_zero_error_obs = .false.,
  verbose
            = .false.
```

Observation-space diagnostics

The observation sequence file is not in a particularly user-friendly format. To aid in the evaluation and interpretation, a program named **obs_diag** must be run to produce a netCDF file with results that can be plotted in a manner of your choosing. DART has Matlab functions/scripts that create high-quality graphics. For up-to-date information on the latest, greatest diagnostics, go to: http://www.image.ucar.edu/DAReS/DART/DART2 Diagnostics.php#obs diagnostics

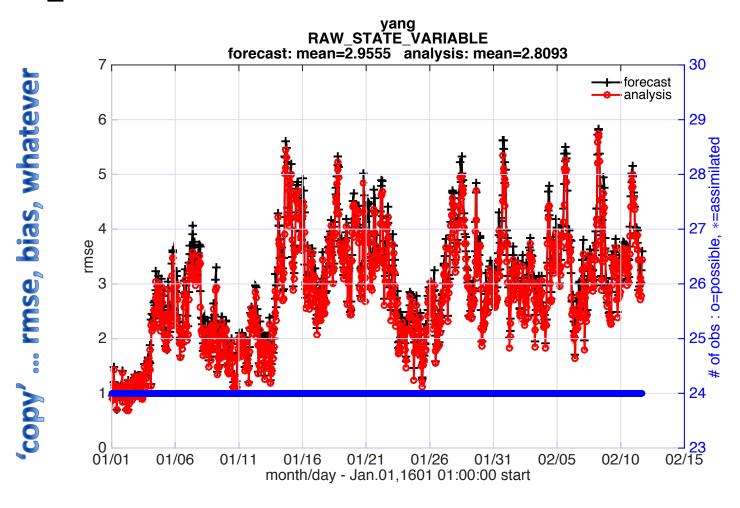
Here are a few of the Matlab functions available in *diagnostics/matlab*

- plot_rank_histogram.m
- plot_evolution.m
- plot_rmse_xxx_evolution.m
- two_experiments_evolution.m
- plot_profile.m
- plot_bias_xxx_profile.m
- plot_rmse_xxx_profile.m
- two_experiments_profile.m

These work with ANY obs_seq.final from ANY experiment with ANY model!

Lorenz 96 observation diagnostic example

outlier_threshold = -1.0



Observation use metrics

data file: /Users/thoar/svn/DART/clean_lanai/models/lorenz_96/work/obs_diag_output.nc

Time (aka 'evolution')

First Observation-space diagnostics:

Try setting the rejection threshold to a small positive number and rerunning *filter*, and then rerunning *obs_diag* on the new output file.

Don't forget to rerun filter!

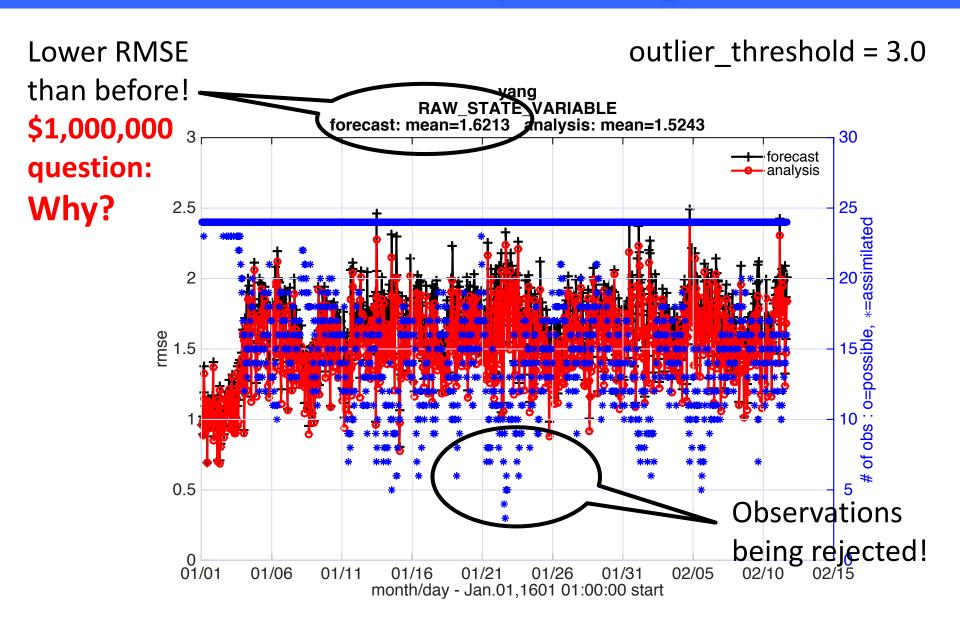
Don't forget to rerun *obs_diag*!

Don't forget to use the right filename in obs_diag_nml!

This is potentially **DANGEROUS**, but useful.

Rejecting 'good' observations can lead to inflated estimate of quality.

First Observation-space diagnostics:

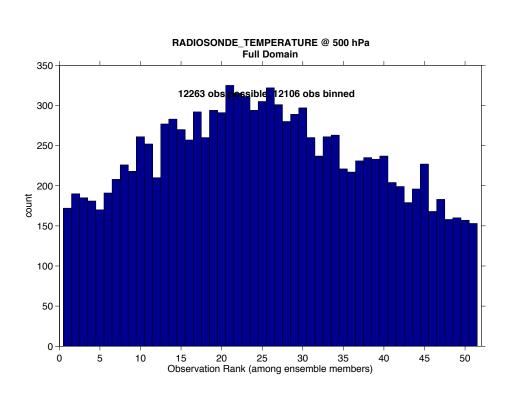


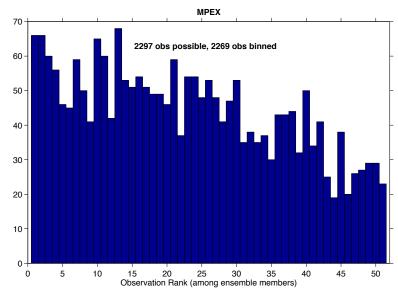
Lorenz_96 exercises:

- Pick a case that works relatively well and look at observation-space diagnostics.
- Pick a case that is similar, but clearly different, with physical-space diagnostics.
- See if you can detect the difference with observationspace diagnostics.
- Rerun obs_diag with different bin_widths.

Observation-space diagnostics: rank histograms

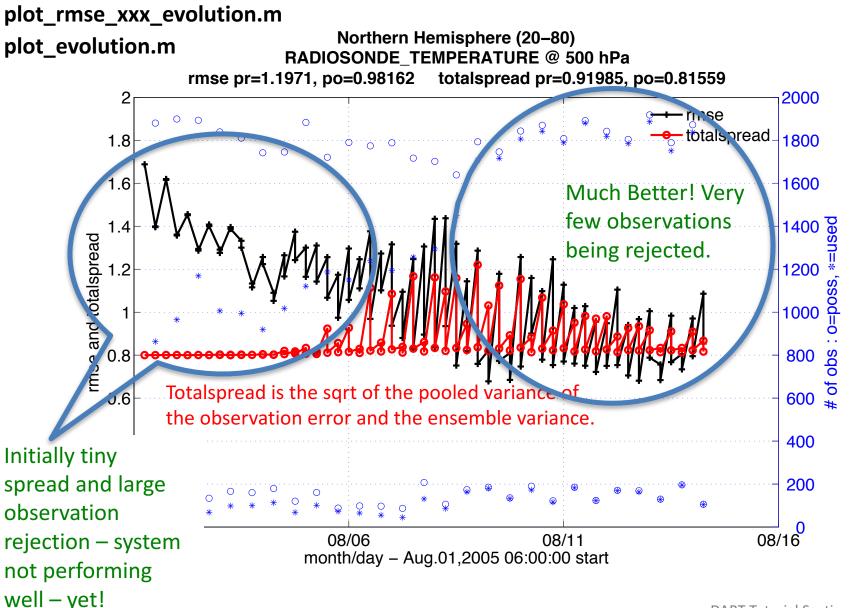
```
>> fname = 'obs_diag_output.nc';
>> timeindex = -1;
>> varname = 'RADIOSONDE_TEMPERATURE';
>> plot_rank_histogram(fname, timeindex, varname);
```





Results from WRF real-time forecasting.

Observation-space diagnostics: time evolution (by level)

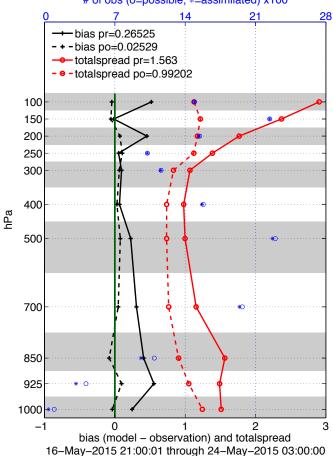


Observation-space diagnostics: time-averaged profiles

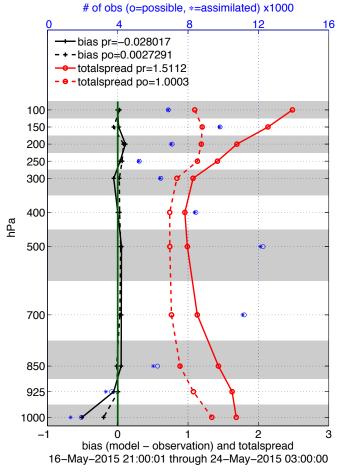
plot_profile.m plot_bias_xxx_profile.mplot_rmse_xxx_profile.m

Note: These are much more informative for models with levels! (i.e. the 1D models are not very interesting this way)

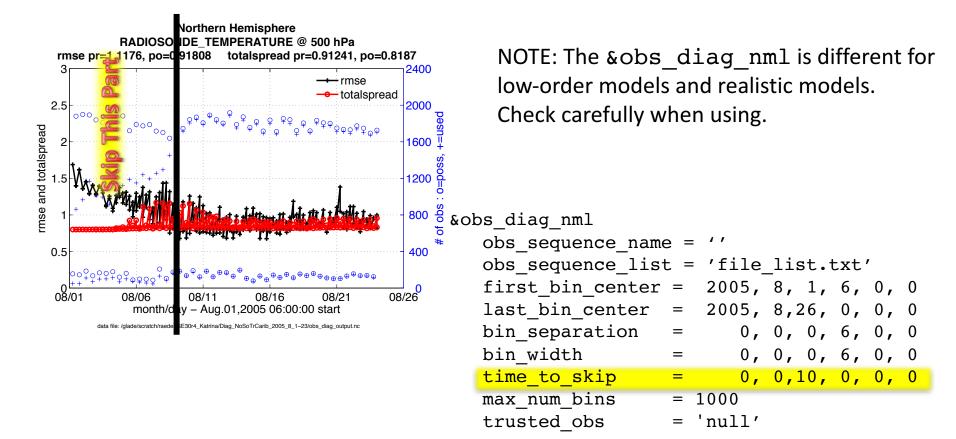
MPEX RADIOSONDE_TEMPERATURE # of obs (o=possible, *=assimilated) x100



Full Domain RADIOSONDE TEMPERATURE



A word of warning ...



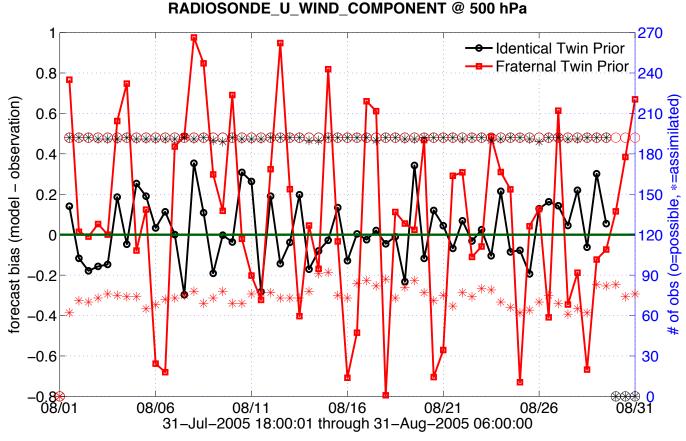
obs_diag 'time_to_skip' setting will allow you to ignore the spinup before starting the time-averaging for the vertical profiles while still calculating metrics for the entire period of record for the time-evolution products.

Observation-space diagnostics: comparing experiments

two_experiments_evolution.m two_experiments_profile.m

This is useful for quick comparisons. Really 'fair' comparisons require more processing to compare the same set of observations across experiments.

assimilation_code/programs obs_common_subset.html obs_seq_coverage.html obs_selection.html obs_seq_verify.html



Southern Hemisphere

FYI:

'Identical' means the model that was used to generate the observations is also used for the assimilation.

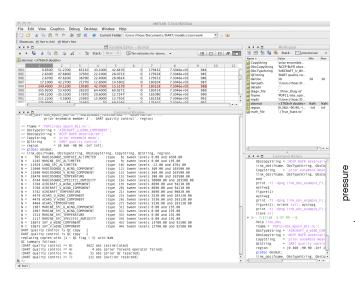
'Fraternal' means the observations came from a different model.

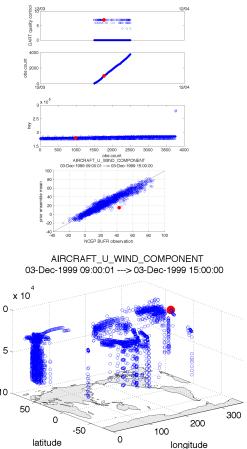
Observation-space diagnostics: netCDF

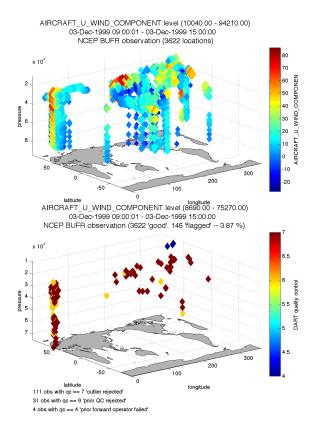
SOME of the information in the observation sequence files can be converted to netCDF and easily plotted. A program named **obs_seq_to_netcdf** must be run to produce the netCDF.

Here are a few of the Matlab functions available in diagnostics/matlab.

- link_obs.m
- plot_obs_netcdf.m
- plot_obs_netcdf_diffs.m
- plot_coverage.m







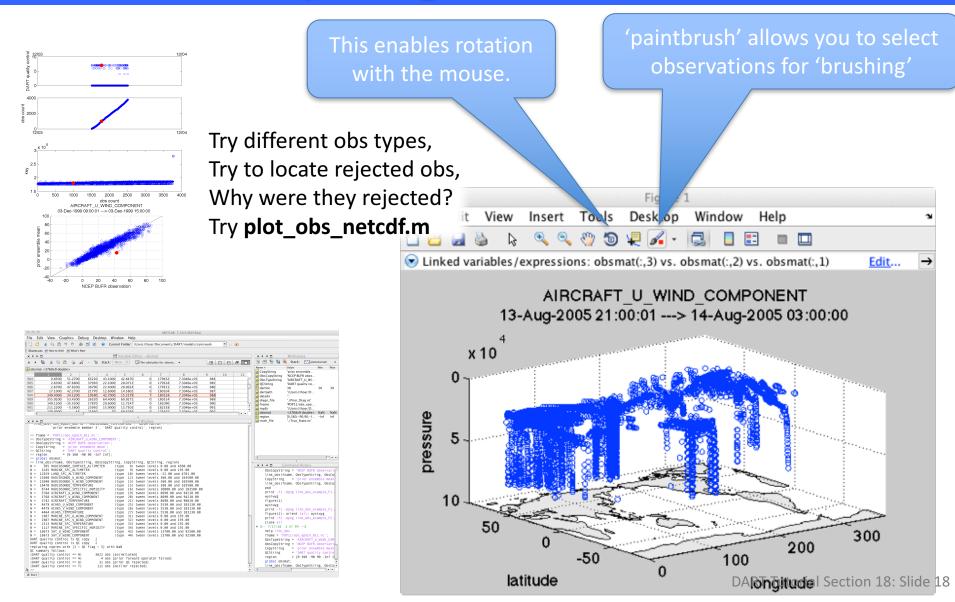
Complicated observation-space diagnostics.

The program **obs_seq_to_netcdf** converts much of the information in an observation sequence file to a netCDF file. For now, we're going to explore a pre-computed file available at:

www.image.ucar.edu/pub/DART/Tutorial_Datasets/obs_epoch_SE30r4_Katrina.nc

It was generated with the following input:

Matlab Hands-On: link_obs exploring observations



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